

Dynamo Basics

Fatima Ebrahimi

Princeton Plasma Physics Laboratory and Dept. of Astrophysical Sciences,
Princeton University

PPPL Graduate Summer School
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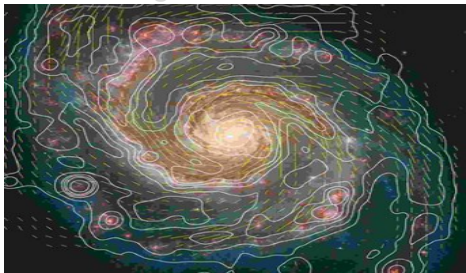
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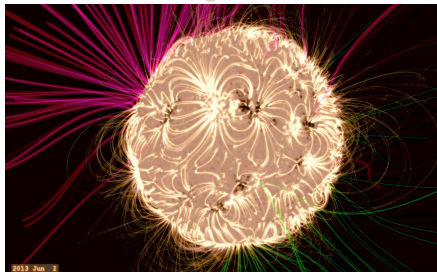
Magnetized universe: magnetic fields are observed to exist essentially everywhere in the universe

- Why is the universe magnetized?
- Observation of large-scale magnetic fields in widely different types of astrophysical objects

Galactic magnetic field



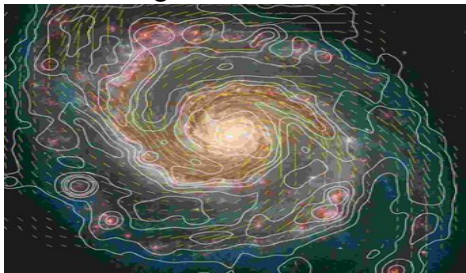
Solar/stellar magnetic field



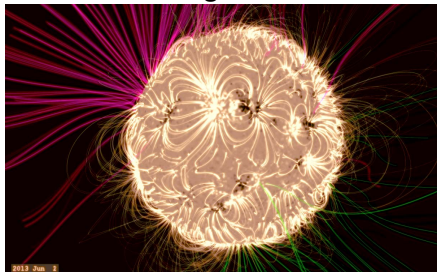
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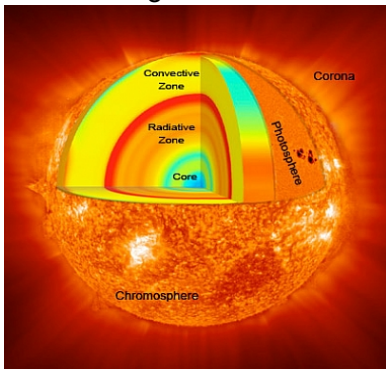


Sun is a natural dynamo engine making magnetic field and energy

(Loading sunexplosion.mp4)

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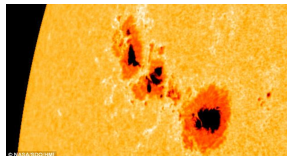
Different regions of sun



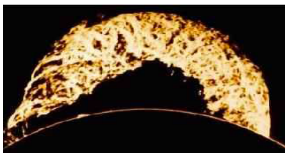
- Core: nuclear fusion extend from center to about $0.2 R$ ($R=696,392$ km) ($T \sim 15$ million K)
 - Radiative zone: heat transfer through thermal radiation ($0.2R-0.7R$) ($T \sim 2-7$ million K)
 - Convective zone: heat transfer through thermal convection from $0.7R$ to the surface ($T \sim 5800k- 2$ million k)
 - Photo-sphere: visible surface of sun with about $400km$ width ($T \sim 6000K$)
- Solar atmosphere:
- 1- chromosphere low temperatures ($4000-100000$ K), width about $2000km$
 - 2- corona (halo during a total eclipse): high temperature about a few million K.
 - 3- Heliosphere regions beyond $20R$.

Solar magnetic fields

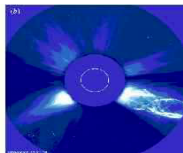
Magnetic field has a key role in understanding major solar events.



Sunspots: very intense magnetic lines of force break through the sun's surface (from 2011)



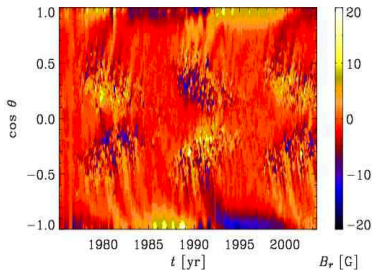
Prominences: long lasting magnetic structures above the surface of the sun (famous “Grand daddy” prominence of 4 June 1946)



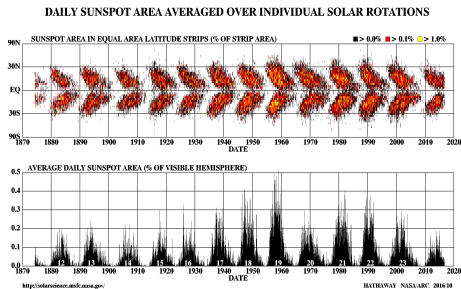
Streamers and loops: structures in the corona shapes by the magnetic fields (big coronal mass eruption of 2 June 1998 from the LASCO chronograph)

Observation: Solar field strength and space-time diagrams

Radial magnetic field alternates in time over the 11 year cycle and also changes sign across the equator.

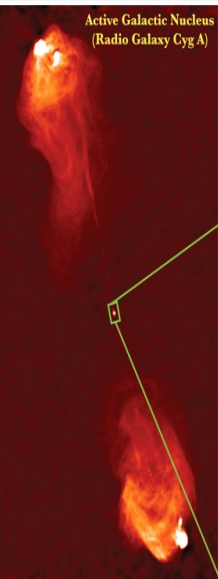


Longitudinally averaged radial component of the observed solar magnetic field as a function of $\cos(\text{colatitude})$ and time. At the solar surface the azimuthally averaged radial field is only a few gauss.

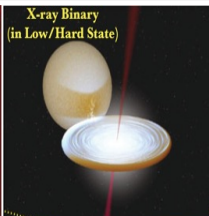


Solar butterfly diagram showing the sunspot number in a space-time diagram. Peak magnetic field in sunspots of about 2 kG. Calculations predict field strengths of about 100kG in the deeper convection zone.

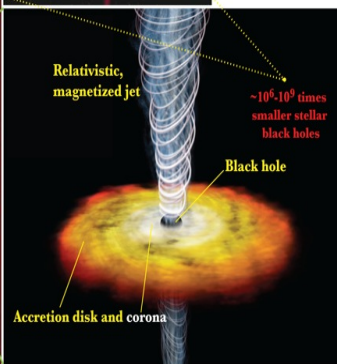
Magnetic field is required to cause accretion, the collimation of jets and star formation.



Active Galactic Nucleus
(Radio Galaxy Cyg A)



X-ray Binary
(in Low/Hard State)

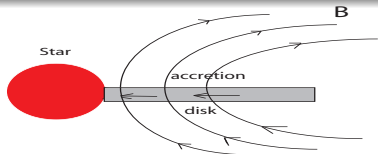


Relativistic,
magnetized jet

$\sim 10^6 - 10^9$ times
smaller stellar
black holes

Black hole

Accretion disk and corona



- What causes gas to be drawn in towards black holes, rather than remain in a stable orbit as planets do around the Sun? [S. Balbus]
- B is required for MHD instabilities to cause accretion.
- Source of field: 1- May be supplied externally may be dragged from larger radii 2- maybe regenerated by local dynamo action

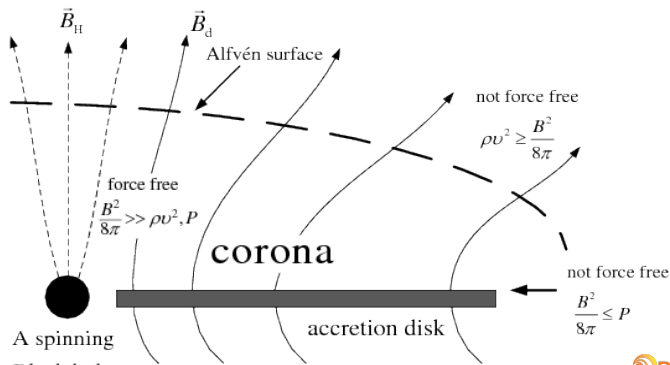
Self-organized plasmas: where dynamo and reconnection are linked

Examples of self-organized plasmas include

Flow-dominated: astrophysical disks (**dynamo**)

Magnetically-dominated: surface of stars (disk and stars coronas) (**reconnection**).

A disk-corona model



from Wang et al. RAA

Observed magnetic fields are believed to be caused by self-exciting dynamo

Dynamo: any device or media that can convert kinetic energy into electromagnetic energy

dynamo effect

kinetic energy =====> magnetic energy

Self-exciting dynamo = No external fields or currents are needed to sustain the dynamo, aside from a weak seed magnetic field to get started.

Why should we care about dynamo problem?

- **Long standing physics challenge:**

Explaining and understanding the origin of observed magnetic fields on all scales in the universe comprises a set of long standing questions in basic plasma astrophysics.

- **Important in laboratory fusion plasmas:**

Plays important roles in laboratory plasmas including reversed field pinches, spheromaks and tokamaks. Local flux amplification/distribution due to the dynamo effect arising from correlated fluctuations can affect:

- stability of the configuration
- current transport
- momentum transport

More on the lab applications in Tuesday's lecture (Prager) and some on Friday (F. E).

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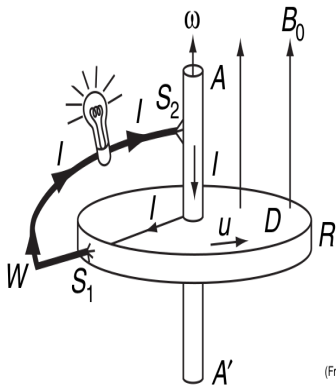
How do we make fields?



- Faraday (1831) discovered the principle of the electromagnetic generator - Faraday disk the first electric generator.

Electric conductor moving in a magnetic field

=> electromotive force => electric current => magnetic field



(From Roberts, 2007)

Current flows, and magnetic field is generated by current (I),
but not reinforcing B_0

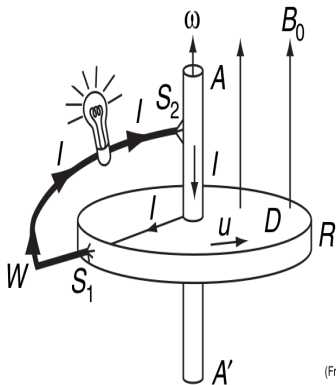
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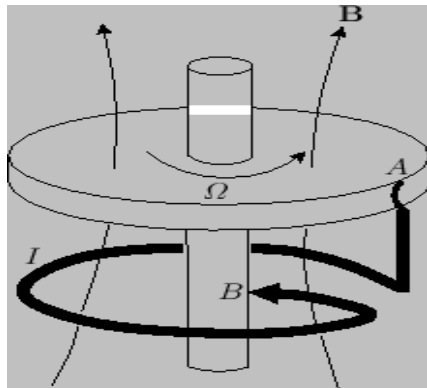
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A simple disk dynamo model

- Larmor (1919) later proposed that the current generated by this process might be able to generate the magnetic field that the system needs. Could that explain solar fields?

Self-excited dynamo

Possible when the wire loops around the disk (Bullard disk 1949)



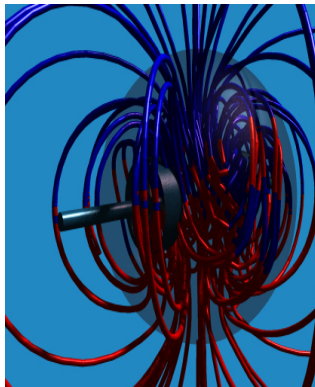
Magnetic field generated by current (I) can now **reinforce** B_0

Too simple to be applicable for astrophysical objects

In reality what do we need for a self-exciting dynamo?

To generate and sustain magnetic fields

- A weak **initial “seed” magnetic field** (which can be removed later).
- A suitable arrangement of the **motions** in an electrically conducting media and current pathways to produce magnetic field
- A **continuous supply of energy** to drive the electrical conductor sufficiently fast for self-excitation to be possible



Let's consider electrically conducting media/fluids, including plasmas. Start with Maxwell equations in the absence of magnetic diffusivities (the ideal case)

$$\text{Ampere's} \Rightarrow \mu_0 \mathbf{J} = \nabla \times \mathbf{B}$$

(Neglecting the displacement current $\mu\epsilon\partial_t E$)

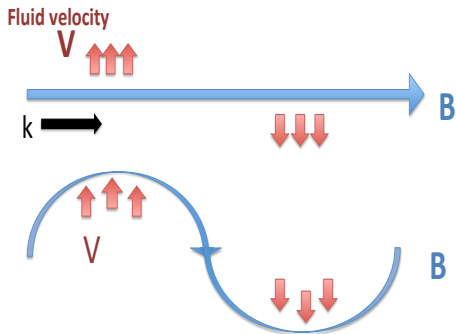
$$\text{Faraday's} \Rightarrow \frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$$

$$\text{Ohm's} \Rightarrow \mathbf{E} = -\mathbf{V} \times \mathbf{B}$$

Induction equation: (magnetic field responds to motion)

$$\frac{d\mathbf{B}}{dt} = \nabla \times (\mathbf{V} \times \mathbf{B})$$

Fluid elements move with the magnetic field.



$$\frac{d\mathbf{B}}{dt} = \nabla \times (\mathbf{V} \times \mathbf{B}) = -(\mathbf{V} \cdot \nabla) \mathbf{B} + \underbrace{(\mathbf{B} \cdot \nabla) \mathbf{V}}$$

bending of lines

Shear

Alfvén waves: $\omega = \mathbf{k} \cdot \mathbf{V}_A$; $\mathbf{V}_A = \frac{\mathbf{B}}{\sqrt{\mu_0 \rho}}$

Hannes Alfvén: 1970 Nobel Prize in physics for his pioneering work on MHD



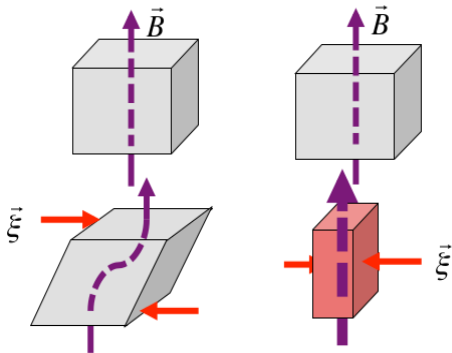
Magnetic field can change by fluid motion

First an ideal case (diffusivities = 0)

$$\nabla \times (\mathbf{V} \times \mathbf{B}) = \underbrace{-\mathbf{V} \cdot \nabla \mathbf{B}}_{\text{convection of fluid / advection}} + \underbrace{(\mathbf{B} \cdot \nabla) \mathbf{V}}_{\text{stretching / bending of lines}} - \underbrace{\mathbf{B}(\nabla \cdot \mathbf{V})}_{\text{compression}}$$

Compression increases B and perpendicular shear bends B

[figure from Sovinec MHD SULI talk]



Magnetic field can change by fluid motion

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↓

Example, consider a linear mean (large-scale) shear flow
 $\mathbf{V} = (0, Sx, 0)$ and $\mathbf{B} = (B_0, 0, 0)$,

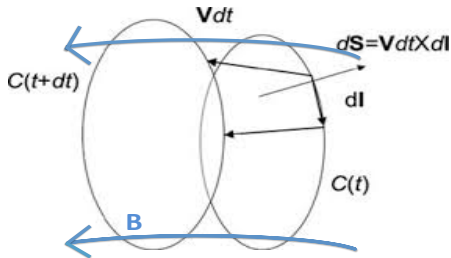
Solution from above $\implies \mathbf{B} = (1, St, 0)B_0$.

A field component in the direction of the flow grows linearly in time.

Stretching term due to flux freezing condition can lead to field amplification

Magnetic flux through a surface S , bounded by a curve C

$$\Phi = \int \mathbf{B} \cdot d\mathbf{S}$$



Magnetic flux through a surface moving with the fluid remains constant in the high-conductivity limit.

Change in flux through a moving surface:

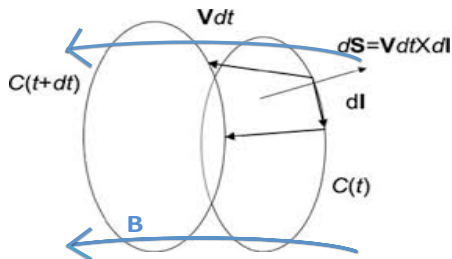
$$\frac{d\Phi}{dt} = \int \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S} + \int \mathbf{B} \cdot \mathbf{V} \times d\mathbf{l} = - \int [\nabla \times (\mathbf{E} + \mathbf{V} \times \mathbf{B})] \cdot d\mathbf{S} = 0$$

(use $\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$ and $\int (\mathbf{V} \times \mathbf{B}) \cdot d\mathbf{l} = \int \nabla \times (\mathbf{V} \times \mathbf{B}) \cdot d\mathbf{S}$)

Stretching term due to flux freezing condition can lead to field amplification

Magnetic flux through a surface S , bounded by a curve C

$$\Phi = \int \mathbf{B} \cdot d\mathbf{S}$$



$$\frac{d\Phi}{dt} = 0$$

For a thin flux tube of length l and cross-section A ,
any shearing motion which increases l will also amplify B ;
An increase in $l \implies$ decrease in A (because of incompressibility)
 \implies increase in B (due to flux freezing)

Let's put back **magnetic diffusivity** into the problem.

$$\text{Ampere's} \Rightarrow \mu_0 \mathbf{J} = \nabla \times \mathbf{B}$$

$$\text{Faraday's} \Rightarrow \frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$$

$$\text{Ohm's} \Rightarrow \mathbf{E} = -\mathbf{V} \times \mathbf{B} + \eta \mathbf{J}$$

$$\frac{\partial \mathbf{B}}{\partial t} + (\mathbf{V} \cdot \nabla) \mathbf{B} = + (\mathbf{B} \cdot \nabla) \mathbf{V} + \eta \nabla^2 \mathbf{B}$$

Magnetic field line stretching competes with diffusion

This effect can be measured with

magnetic Reynolds number $Rm = VL/\eta$

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times \left(\mathbf{V} \times \mathbf{B} + \frac{1}{Rm} \nabla^2 \mathbf{B} \right)$$

Can measure growth in magnetic energy in the volume V

$$\frac{d\mathbf{B}}{dt} = \nabla \times [(\mathbf{V} \times \mathbf{B}) - \eta \mathbf{J}]$$

Dot product of \mathbf{B}/μ_0 with the equation above and integration over the volume gives (HW):

$$\frac{d}{dt} \int \frac{B^2}{2\mu_0} dv = - \int \mathbf{V} \cdot (\mathbf{J} \times \mathbf{B}) dv - \int \eta \mathbf{J}^2 dv - \oint \frac{\mathbf{E} \times \mathbf{B}}{\mu_0} ds$$

Change in magnetic energy

Ohmic dissipation

It means: for the magnetic energy to grow, enough work must be done on the field by the fluid motion (against the Lorentz force) to overcome Ohmic dissipation.

similarly the change of kinetic energy can be shown (dot product of momentum equation with $\rho \mathbf{V}$ and integration):

$$\frac{d}{dt} \int \rho \frac{V^2}{2} dv = \int \mathbf{V} \cdot (\mathbf{J} \times \mathbf{B}) dv + \dots$$

The generation of magnetic energy goes at the expense of kinetic energy, without loss of net energy.

There is a critical Rm for different types of dynamos

$$\frac{d}{dt} \int \frac{B^2}{2\mu_0} dv = - \int \mathbf{V} \cdot (\mathbf{J} \times \mathbf{B}) dv - \int \eta \mathbf{J}^2 dv$$

For a laminar flow (not small-scale), we can have estimates of their magnitudes,

$$\int \mathbf{V} \cdot (\mathbf{J} \times \mathbf{B}) dv \approx (VJB)L^3 \sim V(B/\mu_0 L)BL^3 = V/L(B^2 L^3/\mu_0) \\ \approx V/L(W_B)$$

and

$$- \int \eta \mathbf{J}^2 dv \sim \eta \mathbf{J}^2 L^3 \sim (\eta/\mu_0)(B^2 L^3/\mu_0)/L^2 \approx (\eta/\mu_0)(1/L^2)(W_B)$$

$$\text{For } \frac{d}{dt} \int \frac{B^2}{2\mu_0} dv > 0 \implies Rm \equiv VL/\mu_0\eta > 1$$

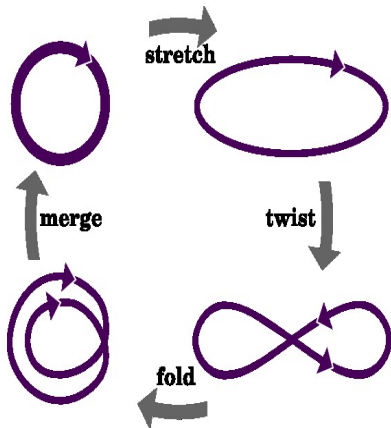
\hookrightarrow **For stretching to win over the diffusion (reconnection)**

$$\implies \boxed{Rm > Rm_{\text{crit}}}$$

Let's put all these pieces of physics together to get magnetic self-enforcement

Zeldovich “Stretch-twist-fold” dynamo : Fast dynamos

The model (1975) illustrates several features of more realistic dynamos.



Stretch: Cross section decreases by 2 (flux freezing) \implies B doubles

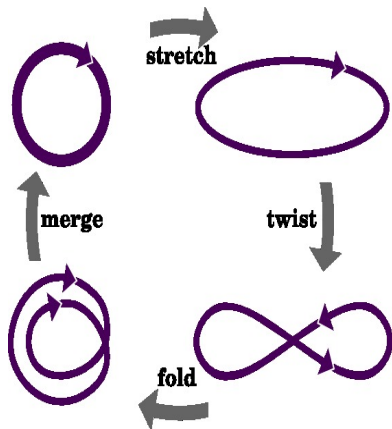
Twist: rope is twisted into figure 8

Fold: then fold, now there are two loops, field points in the same direction (similar volume). Flux through this volume has now doubled!

Two loops merge into one with the help of small diffusivity (process irreversible!)

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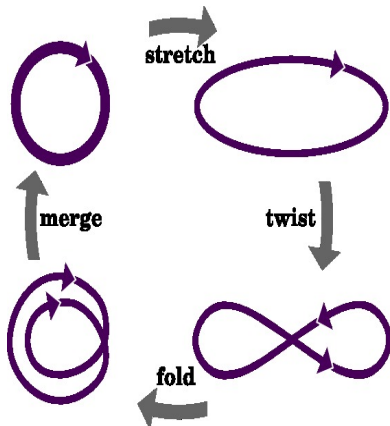
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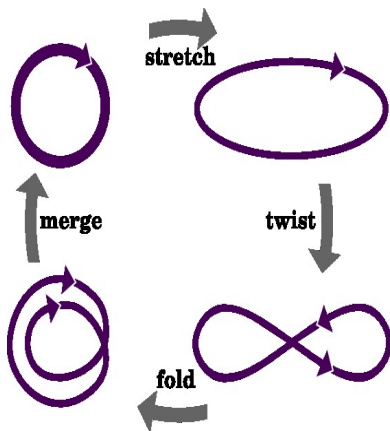
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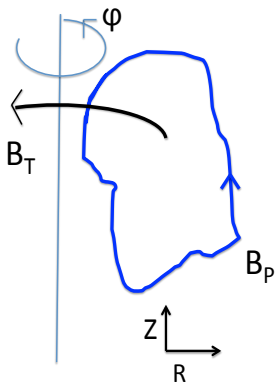
Stretch: To amplify field, **sheared motion** needed

Twist: Twist is needed for the mean field to leave the plane (go to **third direction**)

If only stretch and fold fields cancel.

Need for third dimension: the basis of Cowling theorem

Cowling's theorem: dynamo action in 2-D is not possible



Consider an axisymmetric system
($\partial/\partial\phi = 0$)

$$\frac{\partial \mathbf{A}}{\partial t} = -\mathbf{E} = (\mathbf{v} \times \mathbf{B}) - \eta \mathbf{J} \quad (1)$$

Let $\psi = RA_\phi$ ($\mathbf{B} = \frac{\nabla\psi}{R} \times \hat{\phi}$)
or $RB_R = -\frac{\partial\psi}{\partial z}$, $RB_z = \frac{\partial\psi}{\partial R}$
and $J_\phi = -\nabla \cdot (\frac{1}{R} \nabla\psi)$

The toroidal component of Eq. 1 becomes:

$$\frac{\partial\psi}{\partial t} = \mathbf{v} \times \left[\frac{\nabla\psi}{R} \times \hat{\phi} \right]_\phi + \eta \nabla \cdot \left(\frac{1}{R} \nabla\psi \right)$$

$$\frac{\partial\psi}{\partial t} = -V_p \cdot \nabla\psi + \eta \nabla \cdot \left(\frac{1}{R} \nabla\psi \right) \quad (2)$$

Cowling's theorem: dynamo action in 2-D is not possible

Multiply Eq. 4 by ψ and integrate over space:

$$\frac{\partial}{\partial t} \int \psi^2 dV = - \int \underbrace{\psi \mathbf{V}_p \cdot \nabla \psi}_{\hookrightarrow \nabla \cdot (\mathbf{V}_p \psi^2 / 2)} dV + \eta \int \psi \nabla \cdot \left(\frac{1}{R} \nabla \psi \right) dV \quad (3)$$

RHS becomes:

$$= - \int \frac{\psi^2}{2} \mathbf{V}_p \cdot \hat{\mathbf{n}} dS - \eta \int \frac{1}{R} \psi \hat{\mathbf{n}} \cdot \nabla \psi dS - \eta \int \frac{1}{R} |\nabla \psi|^2 dV$$

The surface integrals vanish if $\mathbf{V}_p \cdot \hat{\mathbf{n}} = 0$ or when scales as $1/r^2$ as $r \rightarrow \infty$ we left with:

$$\frac{\partial}{\partial t} \int \psi^2 dV = -\eta \int \frac{1}{R} |\nabla \psi|^2 dV$$

$$\frac{\partial}{\partial t} \int \psi^2 dV = -\eta \int \frac{1}{R} |\nabla \psi|^2 dV$$

The left hand side must continually decrease with time (as ψ^2 and B_ρ must vanish as $t \rightarrow \infty$), as the right hand side is positive definite (flux decays and impossible in axisymmetric systems).

Other anti-dynamo theorems: A “planar” flow, of the form $(u(x,y,z,t), v(x,y,z,t), 0)$, cannot maintain a magnetic field (Zeldovich's theorem), also dynamo is impossible from purely toroidal flows.

Dynamo requires some ingredient that is symmetry breaking.

1- At what scales magnetic field/energy are generated?

What is the peak of magnetic energy spectrum?

- “Small-scale dynamo” – sustainment of magnetic energy due to magnetic fluctuations in a turbulent state (with a small amount of flux).

Example: galactic clusters

SSD : produces scales below or of the order of forcing scale

- “Large-scale dynamo” – the generation of large-scale field accompanied by the generation of total magnetic flux.

Examples: Systems with rotation, sun, stars, geodynamos, galactic dynamos, disk

LSD: produces fields with spatial coherence , with longterm temporal order (longer than the times-scales of the turbulent motions)

2- Does the dynamo growth depend on Rm ? How fast does the dynamo grow?

- **Fast dynamo**: growth rate can remain finite in the limit $Rm \rightarrow \infty$ (a fast dynamo, whose growth rate does not decrease with decreasing resistivity)
- **Slow dynamo**: magnetic diffusion is crucial for the operation of the dynamo

3- Is it linear or nonlinear?

- **Kinematic dynamo**: for a given a flow $V(x,y,z,t)$, how fast does the magnetic energy grow? Linear, eigenvalue problem (exponential growth of magnetic field which depends on critical Rm)- **There is no feedback from the Lorentz force.**

$$\rho\left(\frac{\partial}{\partial t} - \nu\nabla^2\right)\mathbf{V} = -(\mathbf{V}\cdot\nabla)\mathbf{V} + \cancel{(\mathbf{B}\cdot\nabla)\mathbf{B}} - \nabla P + \mathbf{f}$$

$$\left(\frac{\partial}{\partial t} - \eta\nabla^2\right)\mathbf{B} = -(\mathbf{V}\cdot\nabla)\mathbf{B} + (\mathbf{B}\cdot\nabla)\mathbf{V}$$

$$\nabla \cdot \mathbf{V} = \nabla \cdot \mathbf{B} = 0$$

3- Is it linear or nonlinear?

- **Kinematic dynamo**: for a given a flow $V(x,y,z,t)$, how fast does the magnetic energy grow? Linear, eigenvalue problem (exponential growth of magnetic field which depends on critical Rm)- There is no feedback from the Lorentz force.
- **Nonlinear dynamo**: nonlinear effects begin to modify the flow to limit further growth of the field. Momentum and induction equations are solved simultaneously.

$$\begin{aligned}\rho\left(\frac{\partial}{\partial t} - \nu\nabla^2\right)\mathbf{V} &= -(\mathbf{V}\cdot\nabla)\mathbf{V} + (\mathbf{B}\cdot\nabla)\mathbf{B} - \nabla P + \mathbf{f} \\ \left(\frac{\partial}{\partial t} - \eta\nabla^2\right)\mathbf{B} &= -(\mathbf{V}\cdot\nabla)\mathbf{B} + (\mathbf{B}\cdot\nabla)\mathbf{V} \\ \nabla\cdot\mathbf{V} = \nabla\cdot\mathbf{B} &= 0\end{aligned}$$

$$Rm = VL/\eta, Re = VL/\nu, Pm = Rm/Re.$$

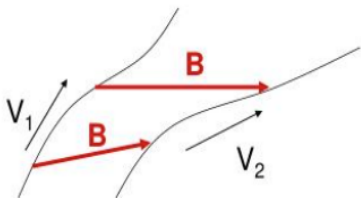
In what dimensional parameter regime is the dynamo operating?

	T [K]	ρ [g cm^{-3}]	P_m	u_{rms} [cm s^{-1}]	L [cm]	R_m
Solar CZ (upper part)	10^4	10^{-6}	10^{-7}	10^6	10^8	10^6
Solar CZ (lower part)	10^6	10^{-1}	10^{-4}	10^4	10^{10}	10^9
Protostellar discs	10^3	10^{-10}	10^{-8}	10^5	10^{12}	10
CV discs and similar	10^4	10^{-7}	10^{-6}	10^5	10^7	10^4
AGN discs	10^7	10^{-5}	10^4	10^5	10^9	10^{11}
Galaxy	10^4	10^{-24}	(10^{11})	10^6	10^{20}	(10^{18})
Galaxy clusters	10^8	10^{-26}	(10^{29})	10^8	10^{23}	(10^{29})

Small Scale Dynamo (SSD)

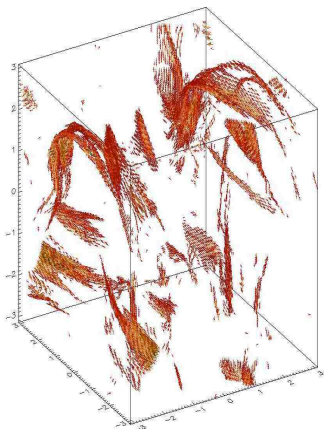
“Small-scale dynamo” – sustainment of magnetic energy due to magnetic fluctuations in a turbulent state with a small amount of flux. Energy generated by forcing through chaotic flows.

SSD could be non-helical dynamos: amplification of magnetic energy via random walk line stretching, folding, and shear.



Smaller (faster) eddies amplify field (size of eddies are at the resistive scale). **Amplification through random walk in a bath of correlated eddies.**

Small Scale Dynamo (SSD)



SSD: generate magnetic field structures

- extending all the way across the domain
- the orientation of these structures is random folded/stretched intermittent structures and not volume filling (see fig.)
- have a correlation length of order smaller than the forcing scales of the flow.

Kinematic turbulent dynamo

- For a given $\mathbf{V}(\mathbf{r},t)$, how would magnetic field grow?
- For example, consider a turbulent velocity field $\mathbf{V}(\mathbf{r},t)$ with a spectrum $k^{-5/3}$ (Kolmogorov), would magnetic energy grow out of turbulent eddies?

Kinematic: no back reaction with momentum equation through Lorentz force.

$$\frac{d\mathbf{B}}{dt} = \nabla \times (\mathbf{V} \times \mathbf{B}) - \frac{\eta}{\mu_0} \nabla^2 \mathbf{B}$$

Two main questions:

- what is the critical magnetic Reynolds number for dynamo?
- what is the characteristic scales of the growing magnetic field (spatial structure)?

SSD theory of Kazantsev (1968) predicted that for a non-helical ($\langle \mathbf{V} \cdot (\nabla \times \mathbf{V}) \rangle = 0$ random (chaotic, zero mean) isotropic, homogeneous flow (delta-correlated in time), dynamo is possible. Simulations needed! Later simulation proved it.

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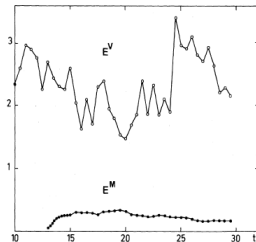
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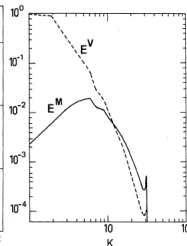
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Forced Small Scale Dynamo - Turbulent dynamo

Energies



Spectra



$$RM = Re = 100$$

- In pioneering work by Meneguzzi, Frisch & Pouquet (1981) full MHD + forcing (feedback through Lorentz force, with a force term \mathbf{f} to drive flow) were solved.
- Turbulent dynamo with nonhelical driving shown

Helical and Nonhelical Turbulent Dynamos

M. Meneguzzi

*Centre National de la Recherche Scientifique and Section d'Astrophysique, Division de la Physique,
Centre d'Etudes Nucleaires de Saclay, F-91191 Gif-Sur-Yvette, France*

and

U. Frisch

Centre National de la Recherche Scientifique, Observatoire de Nice, F-06007 Nice, France

and

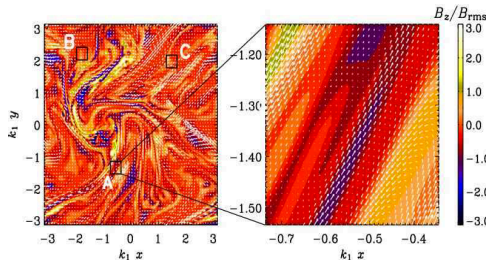
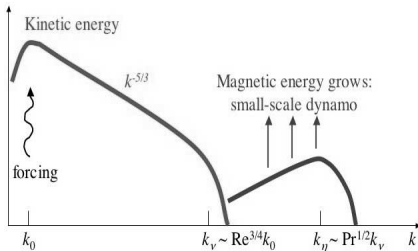
A. Pouquet⁽¹⁾

Centre National de la Recherche Scientifique, Observatoire de Meudon, F-92190 Meudon, France

(Received 13 April 1981)

Direct numerical simulations of three-dimensional magnetohydrodynamic turbulence with kinetic and magnetic Reynolds numbers up to 100 are presented. Spatially intermittent magnetic fields are observed in a flow with nonhelical driving. Small-scale helical driving produces strong large-scale nearly force-free magnetic fields.

Forced SSD simulations at high Pm



Due to random stretching of the magnetic field by the turbulent motions, folded (intermittent) structures are generated.

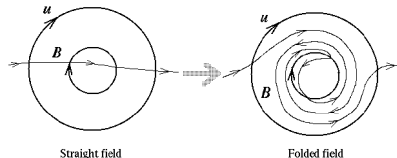
[Cattaneo (1996), Schekochihin et al. (2004), Haugen, Brandenburg 2004].

For dynamo action:

stretching should win ($Rm > Rm_{crit}$)

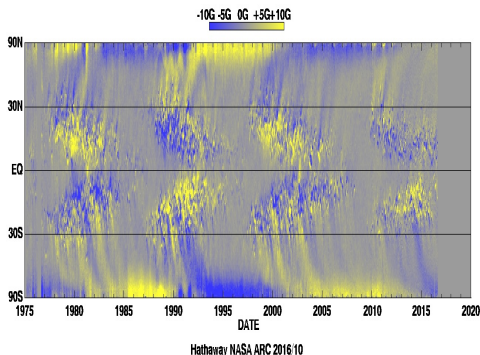
No dynamo:

reconnection wins ($Rm < Rm_{crit}$)



Large-scale dynamo (LSD):

- Dynamo mechanisms that explain the spatial-temporal coherence (regular patterns in space and time which are not random) in astrophysical objects (e. g sun).
- The geometry of the domain and the presence of boundaries and shear are important.

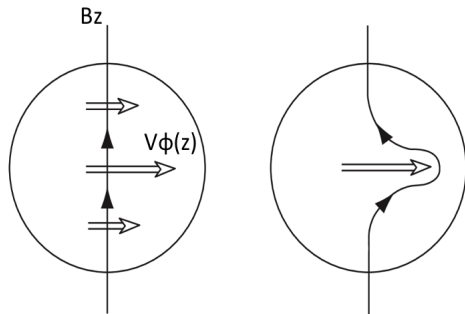


Latitude-time diagram: longitudinally averaged radial component of the observed solar magnetic field
Radial magnetic field alternates in time over the 11 year cycle and also changes sign across the equator.

What is the simplest way that a large-scale field could grow?

Consider: mean seed field + differential rotation

B_0 and $V_\phi(z)$



The Omega-effect:

Conversion of poloidal field to toroidal field by differential rotation (shear) of toroidal flows – (shear of the mean field by differential rotation)

What is the simplest way that a large-scale field could grow?

We go back to the stretching term in the induction equation due to large-scale motions

$$\frac{\partial \overline{\mathbf{B}}_{\text{tor}}}{\partial t} = \overline{\mathbf{B}}_{\text{pol}} \cdot \nabla V_{\text{tor}} + \dots$$

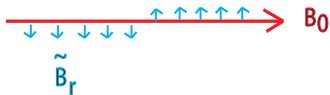
For example consider:

For a poloidal field $B_{\text{pol}} = 3 - 10\text{G}$ (the upper part of the solar convection zone) how much toroidal field is generated in 3 yrs for an $\Omega_{\odot} = 3 \times 10^{-6}\text{s}^{-1}$ (solar angular velocity) and for $\Delta\Omega_{\odot}/\Omega_{\odot} = 0.3$ (a relative latitudinal differential rotation):

$$\Delta B_{\text{tor}} = B_{\text{pol}} \Delta\Omega_{\odot} \Delta T \approx 3 - 10\text{G} \times 10^{-6} \times 10^8 = 0.3 - 1\text{kG}$$

so a 1kG toroidal field can be generated in 3 yrs. However this is too weak to rise up coherently all the way from the convection zone, so other dynamo mechanism effects needed

Could a large-scale field grow out of turbulence?



Consider:

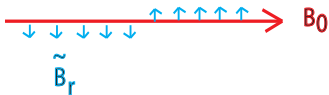
$$V = \langle V \rangle + \tilde{V}$$

$$B = \langle B \rangle + \tilde{B}$$

↑ ↑
large-scale small-scale

- fluctuations : $\tilde{\mathbf{B}}_{mn}(\mathbf{r}) = \tilde{\mathbf{B}}_{mn}(r)e^{i(m\phi - nz + \delta)} + \text{c.c.}$
- $\langle \rangle$, or overbars \rightarrow azimuthally and axially averaged - surface-averaged $\int d\phi dz$
- Reynold Rules $\implies \langle \tilde{\mathbf{B}} \rangle = \langle \tilde{V} \rangle = 0$

Could a large-scale field grow out of turbulence?



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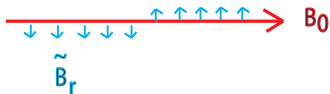
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Consider:

$$V = \langle V \rangle + \tilde{V}$$

$$B = \langle B \rangle + \tilde{B}$$

large-scale small-scale

- fluctuations : $\tilde{\mathbf{B}}_{mn}(\mathbf{r}) = \tilde{\mathbf{B}}_{mn}(r)e^{j(m\phi - nz + \delta)} + \text{c.c.}$
- $\langle \rangle$, or overbars \rightarrow **azimuthally and axially averaged - surface-averaged** $\int d\phi dz$
- Reynold Rules $\implies \langle \tilde{B} \rangle = \langle \tilde{V} \rangle = 0$

Correlated velocity and magnetic field fluctuations give a mean electromotive force (EMF)

Averaging induction equation yields:

$$\frac{\partial \bar{\mathbf{B}}}{\partial t} = \nabla \times (\bar{\mathbf{V}} \times \bar{\mathbf{B}} + \bar{\mathcal{E}}_{emf} - \eta \nabla \times \bar{\mathbf{B}})$$

where

$$\bar{\mathcal{E}}_{emf} \approx \langle \tilde{\mathbf{V}} \times \tilde{\mathbf{B}} \rangle$$

is the mean EMF.

Terms only proportional to $\tilde{\mathbf{V}}$ and $\tilde{\mathbf{B}}$ (and the mean) would not contribute to the **mean** induction equation (due to Reynolds rule).

Quasilinear theory: Fastest (and easiest) way to find out if any fluctuations would produce **nonzero mean EMF and therefore magnetic field** \implies

1- linearize MHD equations to find \tilde{V} and \tilde{B} and

2- construct EMF $\langle \tilde{V} \times \tilde{B} \rangle$ from linear eigenfunctions to evaluate EMFs

what is the nature of EMFs?

Mean field theory: Finding an expression for the correlator $\overline{\mathcal{E}}_{emf}$ in terms of the mean fields i. e.

$$\mathcal{E}_i = \alpha_{ij}(\overline{\mathbf{B}}, \Omega, \dots) B_j + \eta_{ijk}(\overline{\mathbf{B}}, \Omega, \dots) \partial B_j / \partial x_k$$

Tensor components α_{ij} and η_{ijk} are turbulent transport coefficients.

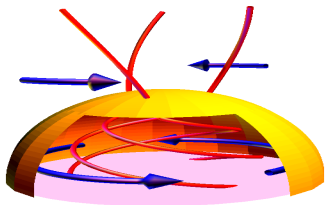
Transport effects that can influence large-scale magnetic fields (Parker, Steenbeck, Krause, Radler, Moffatt).



E. Parker

Alpha effect and shear as a combined dynamo mechanism

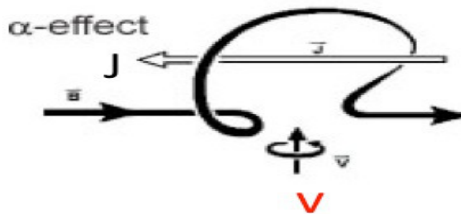
The Ω and α effects.



from Berger 99

Differential rotation provides a strong source of helicity injection and field growth

$$\frac{\partial \bar{\mathbf{B}}}{\partial t} \propto \mathbf{B}_0 \frac{d}{dz} \bar{\mathbf{V}}(z).$$

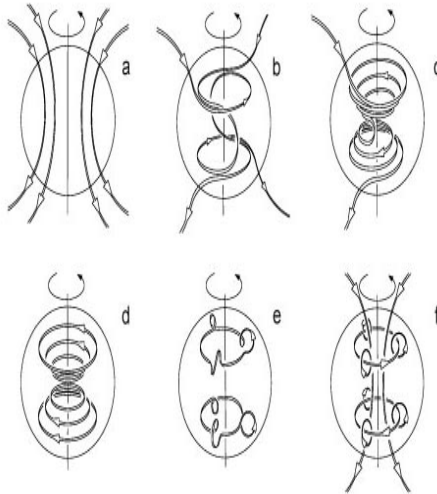


$$\bar{\mathcal{E}}_{emf} = \langle \tilde{\mathbf{V}} \times \tilde{\mathbf{B}} \rangle \approx \alpha \bar{\mathbf{B}}$$

The electromotive force (EMF) from correlated velocity and magnetic field fluctuations

$$\frac{\partial \bar{\mathbf{B}}}{\partial t} = \nabla \times (\bar{\mathbf{V}} \times \bar{\mathbf{B}} + \alpha \bar{\mathbf{B}} - \eta \nabla \times \bar{\mathbf{B}})$$

Alpha-omega mechanism for modeling of astrophysical rotators



through fluid motions (omega effect)



$$\frac{\partial \bar{\mathbf{B}}_{\text{tor}}}{\partial t} = \bar{\mathbf{B}}_{\text{pol}} \cdot \nabla \mathbf{V}_{\text{tor}} + \dots$$

through correlated fluctuations (alpha effect)

$$\leftarrow \frac{\partial \bar{\mathbf{B}}_{\text{pol}}}{\partial t} = \nabla \times \alpha \mathbf{B}_{\text{tor}} + \dots$$

Love, J. J., 1999. *Astronomy & Geophysics*, 40, 6.14-6.19.

Calculations of transport coefficients

$$\begin{aligned}\bar{\mathcal{E}}_{emf} &= \langle \tilde{\mathbf{V}} \times \tilde{\mathbf{B}} \rangle = \langle \tilde{\mathbf{V}} \times \int \frac{\partial \tilde{\mathbf{B}}(t')}{\partial t} dt' \rangle + \langle \int \frac{\partial(\Delta \tilde{\mathbf{V}})}{\partial t} dt' \times \tilde{\mathbf{B}} \rangle \\ &= \langle \int \tilde{\mathbf{V}}(t) \times \nabla \times [\tilde{\mathbf{V}}(t') \times \bar{\mathbf{B}}_0] dt' \rangle + \underbrace{\langle \int (\tilde{\mathbf{J}} \times \bar{\mathbf{B}}_0) dt' \times \tilde{\mathbf{B}} \rangle}_{\text{Back-reaction of magnetic field}}\end{aligned}$$

↓

Back-reaction of magnetic field

$$\propto -\tilde{\mathbf{V}}(t) \times (\tilde{\mathbf{V}} \cdot \nabla) \bar{\mathbf{B}} + \tilde{\mathbf{V}}(t) \times (\bar{\mathbf{B}} \cdot \nabla) \tilde{\mathbf{V}}(t)$$

$$\hookrightarrow -\tilde{\mathbf{V}}(t) \cdot (\nabla \times \tilde{\mathbf{V}}) \bar{\mathbf{B}} + \tilde{\mathbf{V}}^2 \mathbf{J}$$

$$\hookrightarrow = \tilde{\omega} \quad (\text{vorticity})$$

Calculations of transport coefficients (cont.)

$$\begin{aligned}\bar{\mathcal{E}}_{emf} &= \langle \tilde{\mathbf{V}} \times \tilde{\mathbf{B}} \rangle = \langle \tilde{\mathbf{V}} \times \int \frac{\partial \tilde{\mathbf{B}}(t')}{\partial t} dt' \rangle + \langle \int \frac{\partial(\Delta \tilde{\mathbf{V}})}{\partial t} dt' \times \tilde{\mathbf{B}} \rangle \\ &= \langle \int \tilde{\mathbf{V}}(t) \times \nabla \times [\tilde{\mathbf{V}}(t') \times \bar{\mathbf{B}}_0] dt' \rangle + \langle \int (\tilde{\mathbf{J}} \times \bar{\mathbf{B}}_0) dt' \times \tilde{\mathbf{B}} \rangle\end{aligned}$$

Two correlated signals separated by $t - t'$, the average $\langle \tilde{\mathbf{V}}(t) \tilde{\mathbf{V}}(t') \rangle = 0$ when $t - t' > \tau_{\text{corr}}$, so the integral over time can be approximated with τ_{corr} for isotropic turbulence, we get:

$$\bar{\mathcal{E}}_{emf} \sim \alpha \bar{\mathbf{B}}_0 - \eta_t \bar{\mathbf{J}}_0$$

where,

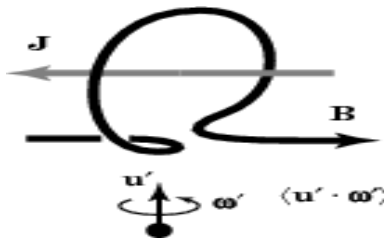
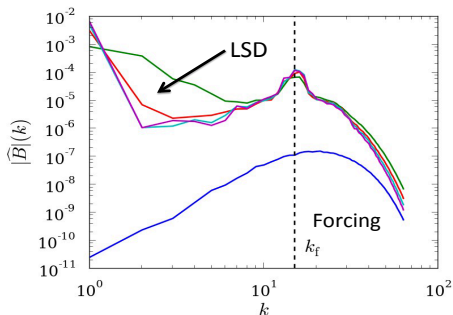
$$\alpha = -\frac{1}{3} \tau_{\text{corr}} \langle \tilde{\mathbf{V}} \cdot \tilde{\omega} \rangle + \frac{1}{3} \tau_{\text{corr}} \langle \tilde{\mathbf{J}} \cdot \tilde{\mathbf{B}} \rangle$$

$$\eta_t = \frac{1}{3} \tau_{\text{corr}} \langle \tilde{\mathbf{V}}^2 \rangle$$

Kinetic helicity can give rise to dynamo

$$\alpha = \underbrace{-\frac{1}{3}\tau_{\text{corr}} \langle \tilde{\mathbf{V}} \cdot \tilde{\boldsymbol{\omega}} \rangle}_{\alpha_k} + \frac{1}{3}\tau_{\text{corr}} \langle \tilde{\mathbf{J}} \cdot \tilde{\mathbf{B}} \rangle$$

Helical flows \rightarrow large-scale fields



The uplifting of helical flows with $\langle \tilde{\mathbf{V}} \cdot \nabla \times \tilde{\mathbf{V}} \rangle \neq 0$ could give an alpha effect.

Back-reaction of the magnetic field modifies the kinematic alpha effect

Back-reaction of the magnetic field on the turbulent flow that generates it (through momentum eq.) modifies the dynamo effect.

$$\alpha = \underbrace{-\frac{1}{3}\tau_{\text{corr}} \langle \tilde{\mathbf{V}} \cdot \tilde{\boldsymbol{\omega}} \rangle}_{\alpha_k} + \underbrace{\frac{1}{3}\tau_{\text{corr}} \langle \tilde{\mathbf{J}} \cdot \tilde{\mathbf{B}} \rangle}_{\alpha_m}$$

The magnetic contribution to the alpha effect with the opposite sign of the kinetic helicity was identified by Pouquet et al. (1976). The term was motivated by the pioneering forced helical nonlinear simulations.



α_m sometimes is called “**current helicity**”, as it is related to magnetic helicity.

Alpha quenching

Using perturbed form of Ohm's law

$$\tilde{\mathbf{E}} = -(\mathbf{V} \times \tilde{\mathbf{B}}) - (\tilde{\mathbf{V}} \times \mathbf{B}) + \eta \tilde{\mathbf{J}} \quad (4)$$

we obtain

$$\langle \tilde{\mathbf{E}} \cdot \tilde{\mathbf{B}} \rangle = \langle \tilde{\mathbf{V}} \times \tilde{\mathbf{B}} \rangle \cdot \bar{\mathbf{B}} + \eta \langle \tilde{\mathbf{J}} \cdot \tilde{\mathbf{B}} \rangle \quad (5)$$

and using

$$\bar{\mathcal{E}}_{emf} \cdot \bar{\mathbf{B}} = \langle \tilde{\mathbf{V}} \times \tilde{\mathbf{B}} \rangle \cdot \bar{\mathbf{B}} \sim \alpha \bar{\mathbf{B}}^2 - \eta_t \bar{\mathbf{J}}_0 \cdot \bar{\mathbf{B}} \quad (6)$$

and $\alpha = \alpha_k + \alpha_M$ We find an equation for the alpha:

$$\alpha = \frac{\alpha_k + \frac{\tau_{corr}}{3\eta\rho} [\eta_t \bar{\mathbf{J}}_0 \cdot \bar{\mathbf{B}} + \langle \tilde{\mathbf{E}} \cdot \tilde{\mathbf{B}} \rangle]}{(1 + \frac{\tau_{corr}}{3\eta\rho} B^2)} \quad (7)$$

$$\alpha = \frac{\alpha_k + \frac{\tau_{\text{corr}}}{3\eta\rho} [\eta_t \bar{\mathbf{J}}_0 \cdot \bar{\mathbf{B}} + \langle \tilde{\mathbf{E}} \cdot \tilde{\mathbf{B}} \rangle]}{(1 + \frac{\tau_{\text{corr}}}{3\eta\rho} B^2)} \quad (8)$$

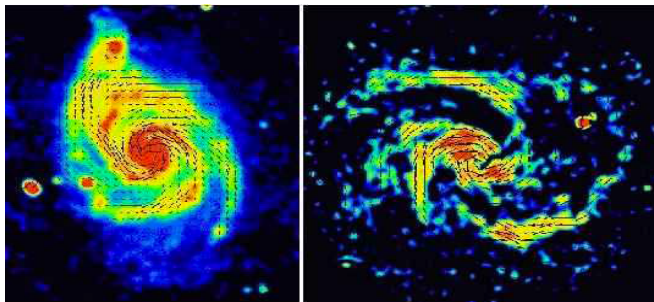
- When the contribution from the $\langle \tilde{\mathbf{E}} \cdot \tilde{\mathbf{B}} \rangle$ is small, and as B increases, α decreases (the so called catastrophic quenching) at high Rm (small η). Cattaneo & Hughes 1996, Blackman&Brandenburg 2002
- For example, in solar interior, $Rm = 10^{10}$ could only lead to saturation of $B \approx 10^{-6}$ T which is much weaker than sunspot fields.
- Some contribution from $\langle \tilde{\mathbf{E}} \cdot \tilde{\mathbf{B}} \rangle$ could suppress the quenching.
- It has been proposed that **magnetic and current helicity fluxes** could alleviate α quenching.

Next Lecture:

- The role of magnetic helicity in the large scale fields
- Theory and simulations link to the observations
- Dynamo in flow-dominated plasmas due to natural instabilities
- Hall dynamos
- Spontaneous plasmoid reconnection

Galactic magnetic fields

Magnetic fields in galaxies are mainly probed using radio observations of their synchrotron emission.



Radio observations of the galaxies M51 and NGC 6946, with superposed magnetic field vectors. Magnetic field (spiral arms) is ordered over large scales. The strength of the total field in the inner spiral arms of M51 is about $30 \mu\text{G}$. The strength of field is typically $1\text{...}5 \mu\text{G}$, and up to $\sim 13 \mu\text{G}$ in the interarm region of NGC 6946